# Aquadopp<sup>®</sup> 2000/6000 m

The most versatile ocean current meters available



Imagine an ocean current meter without need for recalibration, without moving parts, with the ability to withstand fouling and with the sampling volume moved away from the mounting structure.

These are among the factors making the Aquadopp<sup>®</sup> family the most versatile ocean current meters available.

The 6000m Aquadopp<sup>®</sup> is "the big brother" in the line of Aquadopp<sup>®</sup> models. The all-titanium mechanical housing is built to last at great ocean depths. The overall design is the results of a testing and verification process that has included many of the world's largest oceanographic institutions.

Rugged and resistant, the 6000m model still retains all the capabilities of the standard Aquadopp<sup>®</sup>. Built from Titanium grade 2, the instrument is heavier than the standard instrument, but at 8kg, it is still possible to handle one or two units without any lifting equipment.

The 2000m model is made of plastic with a metal cylinder inside. As a result, the 2000m model is lighter than the pure-titanium 6000m model and it represents an affordable alternative for the deployment in intermediate waters.

Both types have a transducer sensor head made from machined Delrin<sup>®</sup> materials with the transducers symmetrically distributed in the horizontal plane while at the same time looking slightly upwards (25°). In the deep ocean, there are fewer suspended particles than in the zone close to the surface. While there are significant variations across the globe, mid-water deployments represent a real challenge for instruments that depend on acoustic backscatter. Considerable work has been done to understand the factors that affect the acoustic signal strength and to improve the magnitude of the returned echo. This work is reflected in the design of the current electronics and 6000m transducer design. Verified performance in the deep ocean is well documented – see our web site for details.

- ✓ No moving parts, no recalibration needed!
- Use Diagnostic mode to measure and get the full picture of mooring motion details.
- Record all relevant parameters including acoustic signal strength, tilt, compass, battery voltage, and status/error code.
- ✓ Set the measurement interval, averaging interval and exact pinging rate independently in the deployment planning menu included as part of the standard software.
- Compass solution includes hard iron calibration routines to remove cable and mounting clamps effects.
- Inquire for other transducer configurations.
- Inquire for special communication options such as acoustic or inductive modems.



## www.nortek.no

### **Specifications**

#### Water Velocity Measurement

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Range	± 3m/s (inquire for higher ranges)
Accuracy	1% of measured value $\pm$ 0.5 cm/s
Maximum sampling	
rate (output)	IHz
Internal sampling rate	23Hz

#### Measurement Area

Measurement cell size 0.75m Measurement cell position 0.35-5.0m (user selectable) Default position 0.35-1.85m (along beam)

#### Doppler Uncertainty (noise)

Typical uncertainty for default configurations 0.5-1.0cm/s Uncertainty in U,V at IHz sampling rate 1.5 cm/s

**Echo Intensity** 

Acoustic frequency Resolution Dynamic range

2MHz 0.45dB 90dB

#### Sensors

Temperature Thermistor embedded in head Range -4°C to 40°C 0.1°C/0.01°C Accuracy/Resolution Time response 10 min Compass Flux-gate with liquid tilt Maximum tilt 30°  $2^{\circ}/0.1^{\circ}$  for tilt <  $20^{\circ}$ Accuracy/Resolution Liquid level Tilt Accuracy/Resolution  $0.2^{\circ}/0.1^{\circ}$  for tilt < 20° Up or down Automatic detect Pressure Piezoresistive 0-2000/6000m (standard) Range Accuracy/Resolution 0.25% / Better than 0.005% of full scale per sample

#### Data Communication

1/0	RS232, analog input, RS422 or analog output. Software supports most commercially available USB–RS232
	converters
Baud rate	300–115200
User control	Handled via Win32 <sup>®</sup> software,
	ActiveX <sup>®</sup> function calls, or direct commands with binary or ASCII data output

#### Software ("Aquadopp DW")

Operating system Windows® 2000, XP Deployment planning, start with Functions alarm, data retrieval, ASCII conversion. Online data collection and graphical display. Test modes

40 bytes

40 bytes

#### Data Recording

Capacity (standard) Data record Diagnostic record

#### Power

DC input Peak current Max consumption IHz Avg. consumption Sleep consumption Battery capacity

9-16VDC 2A at I2VDC (user adjustable) 1.4 W 0.2W (0.02Hz), 0.02W (0.002Hz) 0.0013 W 50 Wh. Extended 6000m version has two battery packs (i.e. double capacity)

9 MB, expandable to 33, 89, or 161MB

New battery voltage Data collection (alkaline) 5 months at 10-min, ± 1.0cm/s noise

13.5 Vdc

LPMBH-8-FS

(10 months for double battery version at 10-min, ± 1.0cm/s noise) Data collection (lithium) 15 months at 10-min, ± 1.0cm/s noise (30 months for double battery version at 10-min, ± 1.0cm/s noise)

#### Connectors

Bulkhead (Impulse)

Cable

**Materials** 

Standard model

Environmental

Storage temperature

Shock and vibration

Pressure rating

2000m: bronze 6000m: titanium PLPMIL-8-MP on 10m polyurethane cable

2000m: Delrin<sup>®</sup> and polyurethane plastics with titanium screws 6000m: Delrin® and titanium

Diameter: 84mm (both types)

Length: 756mm (Extended 6000m)

Length: 597mm (2000m)

Length: 636mm (6000m)

4.4kg(2000m), 8kg (6000m)

#### Operating temperature -5°C to 45°C –20°C to 60°C IEC 721-3-2 0-2000m/0-6000m

**Antifouling Paint** May be applied to all surfaces

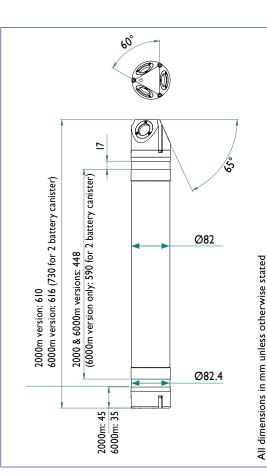
#### Dimensions Cylinder

Approx. weight in air Approx. weight in water 1.2 kg (2000m), 4.8kg (6000m)

#### Options

Battery Head configuration Communication solution Inquire

Lithium batteries Inquire



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